

Enumeration of the monomials of a polynomial and related complexity classes

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- 1 Introduction
- 2 Incremental method
- 3 Polynomial delay method
- 4 Concrete examples and classes
- 5 Conclusion

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Example

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Example

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Example

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The set of monomials of P

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The complexity of all algorithms depends on the number of monomials and often need an a priori bound on this number.

Lemma (Schwarz-Zippel)

Let P be a non zero polynomial with n variables of total degree D , if we chose randomly x_1, \dots, x_n in a set of integers S of size $\frac{D}{\epsilon}$ then the probability that $P(x_1, \dots, x_n) = 0$ is bounded by ϵ .

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Probabilistic algorithm for the *Zero Avoidance Problem*.

Two ways of improving the probability : big evaluation points or repetition

- 1 Introduction
- 2 Incremental method**
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Lemma

Let P be a multilinear polynomial without constant term and L a minimal set of variables such that P_L is not identically zero. Then there is an integer λ such that $P_L = \lambda \vec{X}^L$.

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Lemma

Let P be a multilinear polynomial without constant term and L a minimal set of variables such that P_L is not identically zero. Then there is an integer λ such that $P_L = \lambda \vec{X}^L$.

From now on we assume that the polynomials are **multilinear** without constant term.

We build a set of variable L :

Input : A n variables black box polynomial P

For $i = 1$ **to** n **do**

If $\text{not_zero}(P_{L \setminus \{i\}})$

Then $L = L \setminus \{i\}$

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After this loop, P_L is non zero and L is minimal, with high probability.

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Theorem

The algorithm finds a monomial of a multilinear polynomial given as a black box, with probability $1 - \epsilon$, by making $O(n \log(\frac{n}{\epsilon}))$ calls to the black box on entries of size $\log(2D)$.

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We use this procedure $n + 1$ times : we can bound the total probability of error by ϵ .

We simulate the polynomial $P - Q$ when P is given by a black box and Q explicitly by *subtract*(P , Q).

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Input : A n variables black box polynomial P

$Q \leftarrow 0$

While $not_zero(subtract(P, Q))$

$M \leftarrow find_monomial(subtract(P, Q))$

Write(M)

$Q \leftarrow Q + M$

Theorem

Let P be a multilinear polynomial with n variables, t monomials, C a bound on the size of its coefficient and D its total degree.

Previous algorithm computes the set of monomials of P with probability $1 - \epsilon$. It does $O(tn(n + \log(\frac{1}{\epsilon})))$ calls to the oracle on points of size $2D$. The delay between the i^{th} and $i + 1^{\text{th}}$ found monomials is bounded by $O(iD \max(C, D)n(n + \log(\frac{1}{\epsilon})))$.

- 1 Introduction
- 2 Incremental method
- 3 Polynomial delay method**
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Does P contains a monomial $X^{\vec{e}}$ whose support has no intersection with L_1 but contains L_2 ?

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Does P contains a monomial $X^{\vec{e}}$ whose support has no intersection with L_1 but contains L_2 ?

We have the equality $P_{\bar{L}_1} = \vec{X}^{L_2} P_1(\vec{X}) + P_2(\vec{X})$, by Euclidean division.

Previous question is equivalent to is P_1 zero ?

We assume that the polynomial is multilinear and its coefficients are positive and of size bounded by C .

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A good choice of evaluation points :

$$\left\{ \begin{array}{ll} x_i = 0 & \text{if } i \in L_1 \\ x_i = 2^{n+C} & \text{if } i \in L_2 \\ x_i = 1 & \text{else} \end{array} \right.$$

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$$\begin{cases} x_i = 0 & \text{if } i \in L_1 \\ x_i = 2^{n+C} & \text{if } i \in L_2 \\ x_i = 1 & \text{else} \end{cases}$$

$$P = (2^{n+C})^l P_1(\vec{x}) + P_2(\vec{x})$$

If P_1 is zero, $P(\vec{x}) < 2^{l(n+C)}$

If P_1 is not zero, $P(\vec{x}) \geq 2^{l(n+C)}$

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We can decide the question does P contains a monomial $X^{\vec{e}}$ whose support has no intersection with L_1 but contains L_2 , with one call to the oracle.

We call this procedure *not_zero_improved*(L_1, L_2, P).

A depth first search to enumerate all monomials :

Monomial(L_1, L_2, i) =

If $i = n + 1$

Write The monomial of support L_2

If *not_zero_improved*($L_1 \cup \{i\}, L_2, P$)

Then *Monomial*($L_1 \cup \{i\}, L_2, i + 1$)

If *not_zero_improved*($L_1, L_2 \cup \{i\}, P$)

Then *Monomial*($L_1, L_2 \cup \{i\}, i + 1$

in Monomial($\emptyset, \emptyset, 0$)

Theorem

Let P be a multilinear polynomial with n variables and positive coefficients of size C , t monomials and D its total degree. Previous algorithm computes the set of monomials of P . It does $O(tn)$ calls to the oracle on points of size $O(C + n)$. The delay between the i^{th} and $i + 1^{\text{th}}$ found monomials is bounded by a time $O(n(C + n))$ and $O(n)$ oracle calls.

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The algorithm is easily generalizable to polynomials with arbitrary coefficients, if we make it probabilistic.

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- evaluation points of size $\log(D)$
- incremental delay
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No two monomials of the polynomial have the same support.

It is verified when the polynomial is multilinear.

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Second algorithm :

- evaluation points of size polynomial in n
- polynomial delay
- easy to parallelize

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Example

Let G be a graph with n vertices, we define an $n \times n$ matrix M such that $M_{i,j} = x_{i,j}$ if and only if (i,j) is an edge in G . We associate to G the multilinear polynomial $\det(M)$, whose monomials represents cycle covers of G . The problem of enumerating the monomials is equivalent to enumerating the cycle covers of a graph, which seems a natural problem.

Definition

An enumeration problem A is decidable in probabilistic polynomial total time, written **TotalPP**, if there is a polynomial $Q(x, y)$ and a machine M which solves A with probability greater than $\frac{2}{3}$ and satisfies for all x , $T(x, |M(x)|) < Q(|x|, |M(x)|)$.

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Algorithm of the literature applied to the example = **TotalPP**.

Definition

An enumeration problem A is decidable in probabilistic incremental polynomial time, written **IncPP**, if there is a polynomial $Q(x, y)$ and a machine M which solves A with probability $\frac{2}{3}$ and satisfies for all x , $T(x, i + 1) - T(x, i) \leq Q(|x|, i)$.

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Proposition

ANOTHERSOLUTION_A has a solution in probabilistic polynomial time if and only if $A \in \text{IncPP}$.

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Proposition

ANOTHERSOLUTION_A has a solution in probabilistic polynomial time if and only if $A \in \text{IncPP}$.

First algorithm applied to the example = **IncPP**.

Definition

An enumeration problem A is decidable in probabilistic polynomial delay, written **DelayPP**, if there is a polynomial $Q(x, y)$ and a machine M which solves A with probability $\frac{2}{3}$ and satisfies for all x and all i , $T(x, i + 1) - T(x, i) \leq Q(|x|)$.

Definition

An enumeration problem A is decidable in probabilistic polynomial delay, written **DelayPP**, if there is a polynomial $Q(x, y)$ and a machine M which solves A with probability $\frac{2}{3}$ and satisfies for all x and all i , $T(x, i + 1) - T(x, i) \leq Q(|x|)$.

Second algorithm applied to the example = **DelayPP**.

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It has been proved that Z is the Pfaffian of a matrix, whose coefficients are linear polynomials depending on the hypergraph.

The enumeration of the spanning hypertrees of a 3-uniform hypergraph is in **DelayPP**.

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- 2 Incremental method
- 3 Polynomial delay method
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By combining the two algorithms we can find the monomials of a degree 2 polynomials.

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Question : is it possible to have an incremental algorithm for degree 3 or more ?

$S = [1, n]$ is a set of size n and C be a collection of three elements subsets of S . $C' \subseteq C$, $\chi(C') = \prod_{\{i,j,k\} \in C'} X_i X_j X_k$.

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P_C is the sum of the $\chi(C')$ for all subsets C' . The degree of P_C is the maximal number of occurrences of an element in C .

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$P_C = \prod_{\{i,j,k\} \in C} (X_i X_j X_k + 1)$, which makes it easy to evaluate in polynomial time.

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Remark

A subset C' is an exact cover of S if and only if $\chi(C') = \prod_{i \in S} X_i$.

Assume we have a generalization of the polynomial delay algorithm for degree 3 polynomials : it allows us to test if there is a precise monomial in a polynomial in probabilistic polynomial time.

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Then we can decide if $\prod_{i \in S} X_i$ is in P_C , which is of degree 3 if no elements of S occurs in more than three elements of C . The problem of finding an exact cover even if no element occurs in more than three subsets is NP-complete : it implies that $RP = NP$.

Conjecture : no polynomial delay algorithm for degree 2 or more

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Thanks for listening!